Matrix Calculus Foundation for Machine Learning

LI Xiucheng

SCSE Nanyang Technological University



Background

Matrix Derivative

Matrix Differentiation Rules

Machine Learning Examples

Notation

We denote

- scalars with lower-case, x;
- vectors with bold-case, x;
- matrices with upper-case, X;
- the elements of vectors or matrices with x_i or X_{ij};
- trace as $\operatorname{tr}(X) = \sum_{i=1} X_{ii}$ for $X \in \mathbb{R}^{n \times n}$;
- determinant as |X| for $X \in \mathbb{R}^{n \times n}$;
- matrices Hadamard product as $X \odot Y$;
- vector or matrix inner product with $\langle \cdot, \cdot \rangle$.

Background

For any $\mathbf{x} \in \mathbb{R}^n, \mathbf{y} \in \mathbb{R}^n$ and $X \in \mathbb{R}^{m \times n}, Y \in \mathbb{R}^{m \times n}$, we define their inner product as

•
$$\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^\top \mathbf{y} = \sum_{i=1}^n x_i y_i$$
.

•
$$\langle X, Y \rangle = \operatorname{tr}(X^{\top}Y) = \sum_{i=1}^{m} \sum_{j=1}^{n} X_{ij} Y_{ij}.$$

Remark:

- The second one is also known as matrix Frobenius inner product.
- Frobenius inner product is compatible with vector inner product in the sense that when two matrices degrade to vectors Frobenius inner product equals to vector inner product.

For any $X \in \mathbb{R}^{m \times n}, Y \in \mathbb{R}^{m \times n}, Z \in \mathbb{R}^{m \times n}, a \in \mathbb{R}$,

•
$$\langle X, Y \rangle = \langle Y, X \rangle.$$

•
$$\langle aX, Y \rangle = \langle X, aY \rangle = a \langle X, Y \rangle$$
.

•
$$\langle X+Z,Y\rangle = \langle X,Y\rangle + \langle Z,Y\rangle.$$

•
$$\langle X, Y \odot Z \rangle = \langle X \odot Y, Z \rangle.$$

Suppose that $A \in \mathbb{R}^{m \times \ell_1}, C \in \mathbb{R}^{\ell_1 \times n}, B \in \mathbb{R}^{m \times \ell_2}, D \in \mathbb{R}^{\ell_2 \times n}$, then we have

• $\langle AC, BD \rangle = \langle B^{\top}AC, D \rangle = \langle C, A^{\top}BD \rangle$,

•
$$\langle AC, BD \rangle = \langle ACD^{\top}, B \rangle = \langle A, BDC^{\top} \rangle.$$

Remark

- The first two equations can be summarized as moving left to left by transposing.
- The last two equations can be summarized as moving right to right by transposing.

Proof.

The first two equations are pretty obvious by using the definition of inner product; the last two equations use the fact that tr(XY) = tr(YX) holds for any two matrices X, Y such that X^{\top} has the same size with Y.

Matrix Derivative

Matrix Derivative

Let us denote $f = f(X) \in \mathbb{R}$.

First, consider a scalar x, we have

$$df = f'(x)dx \tag{1}$$

Similarly, for a vector \mathbf{x} , we have that

$$df = \sum_{i=1}^{n} \frac{\partial f}{\partial x_i} dx_i = \langle \nabla_{\mathbf{x}} f, d\mathbf{x} \rangle.$$
(2)

The above form is easy to extend to matrix as

$$df = \sum_{i=1}^{m} \sum_{j=1}^{n} \frac{\partial f}{\partial X_{ij}} dX_{ij} = \langle \nabla_X f, dX \rangle.$$
(3)

Matrix Differentiation Rules

1.
$$d(X \pm Y) = dX \pm dY, d(XY) = (dX)Y + XdY, d(X^{\top}) = (dX)^{\top}$$

2. $d \operatorname{tr}(X) = \operatorname{tr}(dX)$
3. $dX^{-1} = -X^{-1}(dX)X^{-1}$
4. $d|X| = \langle \operatorname{adj}(X)^{\top}, dX \rangle$, where $\operatorname{adj}(X)$ is the adjoint matrix of X
5. $d|X| = |X| \langle (X^{-1})^{\top}, dX \rangle$ when X is invertible
6. $d(X \odot Y) = (dX) \odot Y + X \odot dY$
7. $d\sigma(X) = \sigma'(X) \odot dX$, where $\sigma(\cdot)$ is an element-wise function such as sigmoid

Remark: (1) implies that $d\langle X, Y \rangle = \langle dX, Y \rangle + \langle X, dY \rangle$. (4) is known as Jacobi's formula.

The key idea is to use the properties of inner product and the matrix differentiation rules to obtain the inner product form

 $df = \langle \nabla_X f, dX \rangle.$

Machine Learning Examples

 $f(\mathbf{x}) = \langle \mathbf{x}, A\mathbf{x} \rangle.$

$$df = \langle d\mathbf{x}, A\mathbf{x} \rangle + \langle \mathbf{x}, dA\mathbf{x} \rangle$$
$$= \langle A\mathbf{x}, d\mathbf{x} \rangle + \langle \mathbf{x}, Ad\mathbf{x} \rangle$$
$$= \langle A\mathbf{x}, d\mathbf{x} \rangle + \langle A^{\top}\mathbf{x}, d\mathbf{x} \rangle$$
$$= \langle A\mathbf{x} + A^{\top}\mathbf{x}, d\mathbf{x} \rangle$$

Hence,

$$\nabla_{\mathbf{x}} f = A\mathbf{x} + A^{\top}\mathbf{x}.$$

Linear Regression

$$f(\mathbf{w}) = \langle X\mathbf{w} - \mathbf{y}, X\mathbf{w} - \mathbf{y} \rangle.$$

$$df = \langle d(X\mathbf{w} - \mathbf{y}), X\mathbf{w} - \mathbf{y} \rangle + \langle X\mathbf{w} - \mathbf{y}, d(X\mathbf{w} - \mathbf{y}) \rangle$$

= 2\langle X\mathbf{w} - \mathbf{y}, d(X\mathbf{w} - \mathbf{y}) \rangle
= 2\langle X\mathbf{w} - \mathbf{y}, Xd\mathbf{w} \rangle = 2\langle X^T (X\mathbf{w} - \mathbf{y}), d\mathbf{w} \rangle.

Hence,

$$\nabla_{\mathbf{w}}f = 2X^{\top}(X\mathbf{w} - \mathbf{y}).$$

And

$$abla_{\mathbf{w}}f = 0 \quad \Longrightarrow \quad \mathbf{w}^* = (X^\top X)^{-1} X^\top \mathbf{y}.$$

Softmax Regression

In Softmax regression, **y** is a one-hot vector defining the class target distribution, $\hat{\mathbf{y}} = \text{softmax}(X\mathbf{w})$ is the model predicted distribution. The loss function is defined as the cross-entropy between **y** and $\hat{\mathbf{y}}$, i.e.,

$$f(\mathbf{w}) = -\langle \mathbf{y}, \log \operatorname{softmax}(X\mathbf{w}) \\ = -\left\langle \mathbf{y}, \log \frac{\exp(X\mathbf{w})}{\langle \mathbf{1}, \exp(X\mathbf{w}) \rangle} \right\rangle \\ = -\langle \mathbf{y}, X\mathbf{w} - \mathbf{1} \log \langle \mathbf{1}, \exp(X\mathbf{w}) \rangle \rangle \\ = -\langle \mathbf{y}, X\mathbf{w} \rangle + \log \langle \mathbf{1}, \exp(X\mathbf{w}) \rangle \langle \mathbf{y}, \mathbf{1} \rangle \\ = -\langle \mathbf{y}, X\mathbf{w} \rangle + \log \langle \mathbf{1}, \exp(X\mathbf{w}) \rangle,$$

note that $\langle \mathbf{y}, \mathbf{1} \rangle = 1$.

Softmax Regression

 $f(\mathbf{w}) = -\langle \mathbf{y}, X\mathbf{w} \rangle + \log \langle \mathbf{1}, \exp(X\mathbf{w}) \rangle.$ $df = -\langle \mathbf{y}, X d\mathbf{w} \rangle + \frac{d \langle \mathbf{1}, \exp(X\mathbf{w}) \rangle}{\langle \mathbf{1}, \exp(X\mathbf{w}) \rangle}$ $= -\langle \mathbf{y}, X d\mathbf{w} \rangle + \left\langle \frac{1}{\langle \mathbf{1}, \exp(X\mathbf{w}) \rangle}, \exp(X\mathbf{w}) \odot d(X\mathbf{w}) \right\rangle$ $= -\langle \mathbf{y}, X d\mathbf{w} \rangle + \left\langle \frac{\mathbf{1} \odot \exp(X\mathbf{w})}{\langle \mathbf{1} \exp(X\mathbf{w}) \rangle}, d(X\mathbf{w}) \right\rangle$ $= -\langle \mathbf{y}, Xd\mathbf{w} \rangle + \left\langle \frac{\exp(X\mathbf{w})}{\langle \mathbf{1}, \exp(X\mathbf{w}) \rangle}, Xd\mathbf{w} \right\rangle$ $= -\left\langle X^{\top}\left(\mathbf{y} - \frac{\exp(X\mathbf{w})}{1-\exp(X\mathbf{w})}\right), d\mathbf{w} \right\rangle$

Hence,

$$abla_{\mathbf{w}} f = X^{ op} rac{\exp(X\mathbf{w})}{\langle \mathbf{1}, \exp(X\mathbf{w})
angle} - -X^{ op} \mathbf{y}$$

Estimating the Covariance of Gaussian Distribution

$$\begin{split} f(\Sigma) &= \log |\Sigma| + \frac{1}{N} \sum_{i=1}^{N} \left\langle \mathbf{x}_{i} - \boldsymbol{\mu}, \Sigma^{-1} (\mathbf{x}_{i} - \boldsymbol{\mu}) \right\rangle. \text{ The first term} \\ & d \log |\Sigma| = |\Sigma|^{-1} d |\Sigma| = \langle \Sigma^{-1}, d\Sigma \rangle. \end{split}$$

The second term

$$egin{aligned} &drac{1}{N}\sum_{i=1}^Nig\langle \mathbf{x}_i-\mu, \Sigma^{-1}(\mathbf{x}_i-\mu)ig
angle &=rac{1}{N}\sum_{i=1}^Nig\langle \mathbf{x}_i-\mu, d\Sigma^{-1}(\mathbf{x}_i-\mu)ig
angle \ &=rac{1}{N}\sum_{i=1}^Nig\langle \mathbf{x}_i-\mu, \Sigma^{-1}(d\Sigma)\Sigma^{-1}(\mathbf{x}_i-\mu)ig
angle \ &=rac{1}{N}\sum_{i=1}^Nig\langle \Sigma^{-1}(\mathbf{x}_i-\mu)(\mathbf{x}_i-\mu)^{ op}\Sigma^{-1}, d\Sigmaig
angle \,. \end{aligned}$$

Let
$$S = \frac{1}{N} \sum_{i=1}^{N} (\mathbf{x}_i - \boldsymbol{\mu}) (\mathbf{x}_i - \boldsymbol{\mu})^{ op}$$
, then $df = \left< \Sigma^{-1} - \Sigma^{-1} S \Sigma^{-1}, d\Sigma \right>.$ Hence,

$$abla_{\Sigma} f = (\Sigma^{-1} - \Sigma^{-1} S \Sigma^{-1})^{ op}.$$